(7 pages) Reg. No. :	p c	a program which translates an assembly language program into a machine language program is alled  (b) Assembler		
	(			
M.Sc. (CBCS) DEGREE EXAMINATION,	(	c) Accumulator (d) Interpreter		
APRIL 2024.	з. Т	To reduce time in transferring bulk data which controller is used?		
Second Semester				
Physics – Elective	(	a) Counter (b) Timer		
MICROPROCESSOR 8085 AND MICRO	. (	c) Interrupt (d) DMA		
CONTROLLER 8051.	4. I	f a stepper motor has 200 steps per revolution		
(For those who joined in July 2023 onwards)		hen the step angle is		
Time: Three hours Maximum: 75 marks	(	a) 1.8° (b) 0.72°		
PART A — $(15 \times 1 = 15 \text{ marks})$	(	c) 7.5° (d) 2°		
Answer ALL questions.	5. A	ADC is otherwise known as		
Choose the correct answer:	(	a) Multiplexer (b) Demultiplexer		
1. Which addressing mode has no memory referencing in 8085 μP?		c) Encoder (d) Decoder		
(a) Immediate (b) Indirect	6. I	n general, a seven segment display contains		
(c) Memory (d) Register		LEDs.		
	(	a) 5 (b) 7		
		c) 6 (d) 8		
		Page 2 Code No. : 5790		

7.	8051 microcontrollers generally have ————priority interrupts.		13. When the microcontroller is turned on, all interrupts are ———— by default				
	(a)	16-level		8-level		(a) Enabled (b) Disabled	
	(c)	2-level	(d)	4-level		(c) Executed (d) Undefined	
8.	How many timers are there in 8051?		14.	DAC converts ———— sent by the			
	(a)	Two 8-bit		Two 16-bit		microprocessor.	
	(c)	One 8-bit	(d)	One 16-bit		(a) Digital voltage only	
9.	In 8051 micro controller, the internal RAM size is			(b) Digital current only			
	(a)	32 byte	(b)	64 byte		(c) Analog voltage or current	
	(c)	128 byte	(d)	256 byte		(d) Analog voltage only	
10.	SWAP A instruction interchanges the low-order and high-order nibbles to the				15.		
	(a)	Register pair	(b)	Accumulator			
	(c)	Memory	(d)	Counter		(a) Orderness (b) Deformation	
11.	Which interrupt has the highest priority in 8051?			hest priority in 8051?		(c) Formation (d) Undefined	
	(a)	TRAP	(b)	RST 6.5		PART B — $(5 \times 4 = 20 \text{ marks})$	
	(c)	RST 7.5	(d)	RST 8.5		Answer ALL questions, choosing either (a) or (b).	
12.	Which of the following is not an addressing mode of 8051?			Each answer should not exceed 250 words.			
	(a)	Register instruct	ions		16.	(a) Describe memory and I/O interfacing.	
	(b) Register specific instructions			ections		$\operatorname{Or}$	
	(c)	Indexed addressi	ing			(b) Show the control word format and explain	
	(d)	None				how each bit is programmed.	
		Paş	ge 3	Code No. : 5790		Page 4 Code No. : 5790 [P.T.O.]	

17. (a) Explain how temperature is measured using steeper motor interfacing.

Or

- (b) Draw the schematic for interfacing a stepper motor with 8085 microprocessor.
- 18. (a) Explain the register set of 8051 microcontroller.

Or

- (b) Draw the organization of input and output pins in 8051 microcontroller.
- 19. (a) Detail the working of PUSH and POP instructions.

Or

- (b) Explain how subroutine is working in 8051 microcontroller.
- 20. (a) Explain the serial communication interrupts and programming in 8051 microcontroller.

Or

(b) How to interface a seven segment display using 8051 microcontroller?

Page 5 Code No.: 5790

PART C —  $(5 \times 8 = 40 \text{ marks})$ 

Answer ALL questions choosing either (a) or (b).

Each answer should not exceed 600 words.

21. (a) List out the addressing modes of 8085 microprocessor and explain each with an example.

Or

- (b) With neat block diagram explain PPI.
- (a) Explain the seven segment display interface with microprocessor.

Or

- (b) Describe the interfacing of digital to analog and analog to digital conversion.
- 23. (a) Draw the pin diagram of 8051 microcontroller and explain its features.

Or

(b) Explain the program memory and data memory structure of 8051 microcontroller.

Page 6 Code No.: 5790

24. (a) Mention various arithmetic operations performed in assembly language of 8051 microcontroller?

Or

- (b) Explain Jump and Call instructions of 8051 microcontroller with an example and mention the difference between Jump and Call operations.
- 25. (a) Define interrupt and state how to enable and disable the interrupts of 8051 microcontroller.

Or

(b) Explain how voltage is measured using steeper motor interfacing in 8051 microcontroller.